

- Slider Type
- Mini
- Standard
- Controllers Integrated
- Rod Type
- Mini
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- Controllers Integrated
- Table/Arm/Flat Type
- Mini
- Standard
- Gripper/Rotary Type
- Linear Servo Type
- Cleanroom Type
- Splash-Proof
- Controllers
- PMEC/AMEC
- PSEP/ASEP
- ROBO NET
- ERC2
- PCON
- ACON
- SDON
- PSEL
- ASEL
- SSEL
- XSEL
- Pulse Motor
- Servo Motor (24V)
- Servo Motor (200V)
- Linear Servo Motor

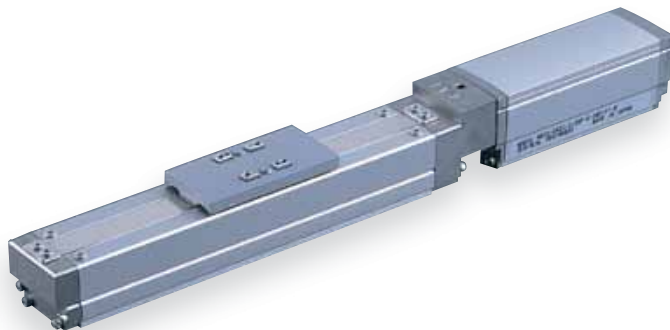
RCP3-SA3C ROBO Cylinder Slider Type 32mm Width Pulse Motor Coupled

■ Configuration: **RCP3** — **SA3C** — **I** — **28P** — — — — —

Series — Type — Encoder — Motor — Lead — Stroke — Compatible Controllers — Cable Length — Option

I: Incremental 28P: Pulse motor 6S: 6mm lead screw 50: 50mm
 * The Simple absolute encoder models are labeled as "I". 28 □ size 4S: 4mm lead screw 300: 300mm (50mm pitch increments)
 P1: PCON RPCON PSEL P3: PMECPSEP
 N: None P: 1m S: 3m M: 5m X □ □: Custom Length
 See Options below

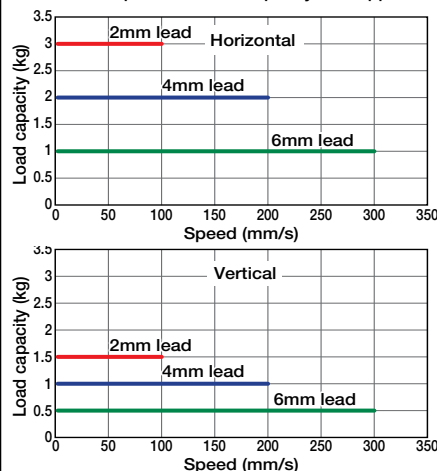
* See page Pre-35 for explanation of each code that make up the configuration name.



Technical References A-5

- POINT** Notes on Selection
- Since the RCP3 series use a pulse motor, the load capacity decreases at high speeds. Check in the Speed vs. Load Capacity graph to see if your desired speed and load capacity are supported.
 - The load capacity is based on operation at an acceleration of 0.3G (0.2G for 2mm-lead model, or when used vertically). These values are the upper limits for the acceleration.

■ Speed vs. Load Capacity
 Due to the characteristics of the pulse motor, the RCP3 series' load capacity decreases at high speeds. In the table below, check if your desired speed and load capacity are supported.



Actuator Specifications

■ Lead and Load Capacity

Model	Lead (mm)	Max. Load Capacity		Maximum Push Force (N)	Stroke (mm)
		Horizontal (kg)	Vertical (kg)		
RCP3-SA3C-I-28P-6-①-②-③-④	6	1	0.5	15	50~300 (50mm increments)
RCP3-SA3C-I-28P-4-①-②-③-④	4	2	1	22	
RCP3-SA3C-I-28P-2-①-②-③-④	2	3	1.5	44	

Legend ① Stroke ② Compatible controller ③ Cable length ④ Options (Unit: mm/s)

■ Stroke and Maximum Speed

Lead	Stroke	50 ~ 300 (50mm increments)	
		Stroke	Maximum Speed
6	6	300	
4	4	200	
2	2	100	

① Stroke List

Stroke (mm)	Standard Price	
	With cover (standard)	No cover (Option)
50	-	-
100	-	-
150	-	-
200	-	-
250	-	-
300	-	-

③ Cable List

Type	Cable Symbol	Standard Price
Standard (Robot Cables)	P (1m)	-
	S (3m)	-
	M (5m)	-
Special Lengths	X06 (6m) ~ X10 (10m)	-
	X11 (11m) ~ X15 (15m)	-
	X16 (16m) ~ X20 (20m)	-
		-

* The standard cable is the motor-encoder integrated robot cable.
 * See page A-39 for cables for maintenance.

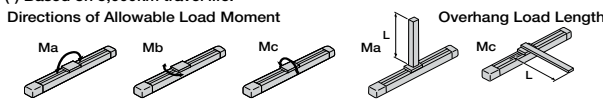
④ Option List

Name	Option Code	See Page	Standard Price
Brake-Equipped	B	→ A-25	-
Cable Exit Direction (Top)	CJT	→ A-25	-
Cable Exit Direction (Right)	CJR	→ A-25	-
Cable Exit Direction (Left)	CJL	→ A-25	-
Cable Exit Direction (Bottom)	CJB	→ A-25	-
No Cover	NCO	→ A-33	-
Reversed-home	NM	→ A-33	-

Actuator Specifications

Item	Description
Drive System	Ball screw Ø6mm C10 grade
Positioning Repeatability	±0.02mm
Lost Motion	0.1mm or less
Base	Material: Aluminum (special alumite treated)
Allowable Static Moment	Ma: 5.0N·m Mb: 7.1N·m Mc: 7.9 N·m
Allowable Dynamic Moment(*)	Ma: 1.96N·m Mb: 2.84N·m Mc: 3.14N·m
Overhang Load Length	100mm or less
Ambient Operating Temp./Humidity	0~40°C, 85% RH or less (non-condensing)

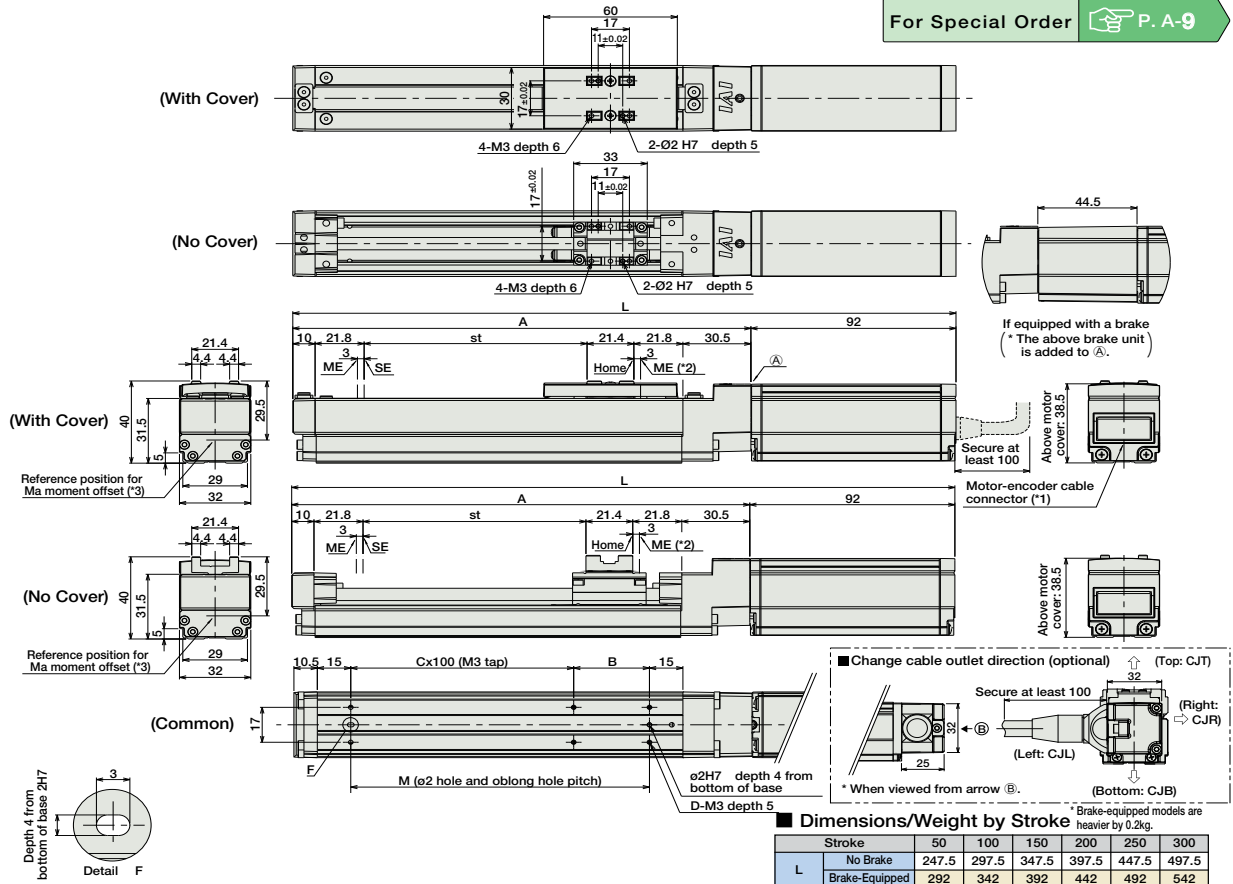
(*) Based on 5,000km travel life.



7 RCP3-SA3C

Dimensions

For Special Order P. A-9



- (*1) A Motor-encoder cable (integrated) is connected here. (See page A-39 for details on cables.)
- (*2) After homing, the slider moves to the ME, therefore, please watch for any interference with surrounding objects.
ME : Mechanical end
SE : Stroke end
- (*3) Reference position for calculating the moment Ma

Dimensions/Weight by Stroke * Brake-equipped models are heavier by 0.2kg.

Stroke	50	100	150	200	250	300	
L	No Brake	247.5	297.5	347.5	397.5	447.5	497.5
	Brake-Equipped	292	342	392	442	492	542
A	155.5	205.5	255.5	305.5	355.5	405.5	
B	84	34	84	34	84	34	
C	0	1	1	2	2	3	
D	4	6	6	8	8	10	
M	84	134	184	234	284	334	
Weight (kg)	With Cover	0.7	0.7	0.8	0.9	0.9	1
	No Cover	0.6	0.7	0.7	0.8	0.8	0.9

② Compatible Controllers

The RCP3 series actuators can operate with the controllers below. Select the controller according to your usage.

Name	External View	Model	Description	Max. Positioning Points	Input Voltage	Power Supply Capacity	Standard Price	See Page	
Solenoid Valve Type		PMEC-C-28PI-NP-2-①	Easy-to-use controller, even for beginners	3 points	DC24V	2A Max.	-	→ P477	
		PSEP-C-28PI-NP-2-0	Operable with same signal as solenoid valve. Supports both single and double solenoid types. No homing necessary with simple absolute type.						
Splash-Proof Solenoid Valve Type		PSEP-CW-28PI-NP-2-0							
		PSEP-CW-28PI-NP-2-0							
Positioner Type		PCON-C-28PI-NP-2-0	Positioning is possible for up to 512 points	512 points					
Safety-Compliant Positioner Type		PCON-CG-28PI-NP-2-0							
Pulse Train Input Type (Differential Line Driver)		PCON-PL-28PI-NP-2-0	Pulse train input type with differential line driver support	(-)					→ P525
Pulse Train Input Type (Open Collector)		PCON-PO-28PI-NP-2-0	Pulse train input type with open collector support						
Serial Communication Type		PCON-SE-28PI-N-0-0	Dedicated to serial communication	64 points					
Field Network Type		RPCON-28P	Dedicated to field network	768 points	→ P503				
Program Control Type		PSEL-C-1-28PI-NP-2-0	Programmed operation is possible. Can operate up to 2 axes.	1500 points		→ P557			

* This is for the single-axis PSEL.
* ① is a placeholder for the power supply voltage (1: 100V / 2: 100~240V).

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